### **Automation of Cone Crushers**

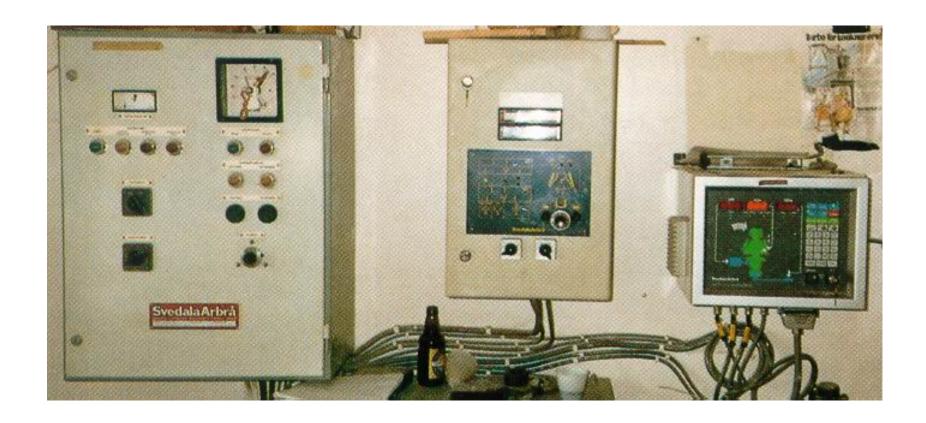
Alex Scott
Sandvik Rock Processing







## Intro - ASR

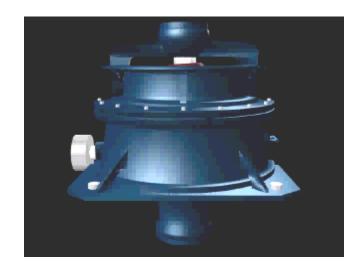








# Principle of operation





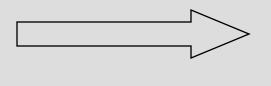


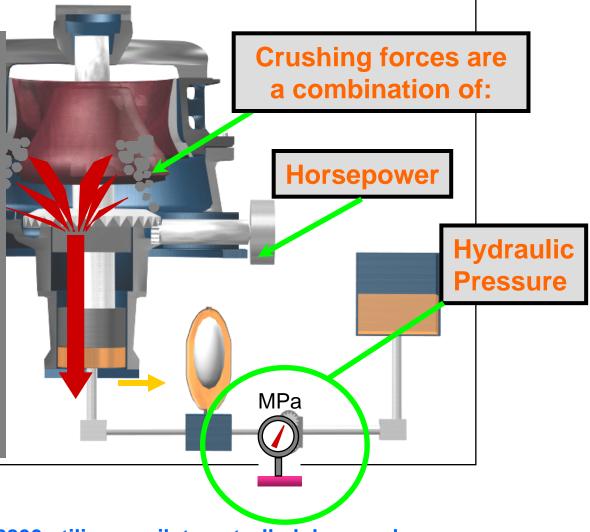


# **Hydraulic Supported Design**

#### SINGLE SYSTEM

- Maintaining and adjusting CSS
- Tramp release
- Chamber clearing
- True automation
- Crushing force







The H8800 utilizes a pilot controlled dump valve





## Factors affecting crusher load

- Material toughness
- Material feedanalysis
- Reduction CSS
- Volume Throw
- Moisture







# History

- 60's research
- Manually controlled crushers 65% 70% utilised
- Why to prevent motor stalls







### Underfeeding results in:

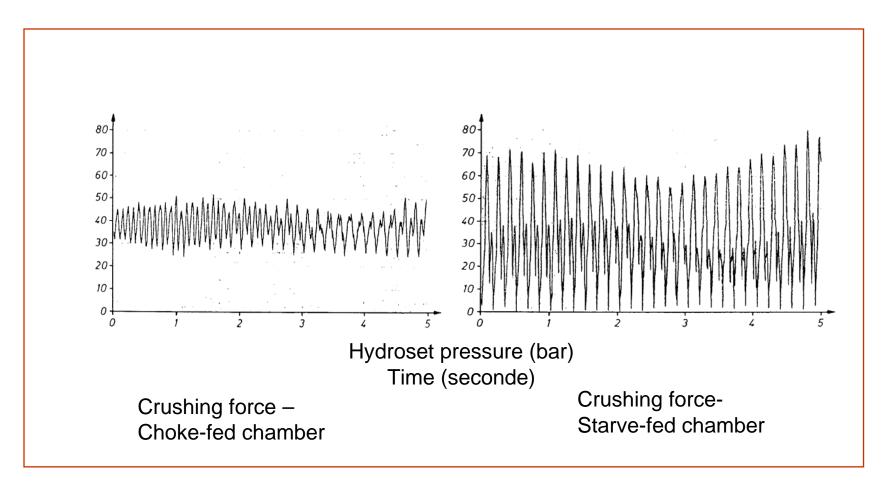
- Increased capital costs additional machines
- Throughput reduction to reduce load downstream
- Increased revenge cost greater power to crush convey oversize
- Wear on screens, conveyor belts chutes, crusher liners
- Reduced product quality







#### Starved-fed crusher means high and uneven load



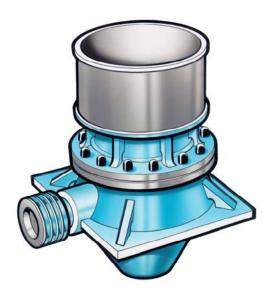


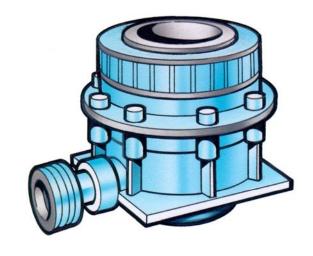




#### **Automation of Cone Crushers**

- > Internal Automation
- > External Automation



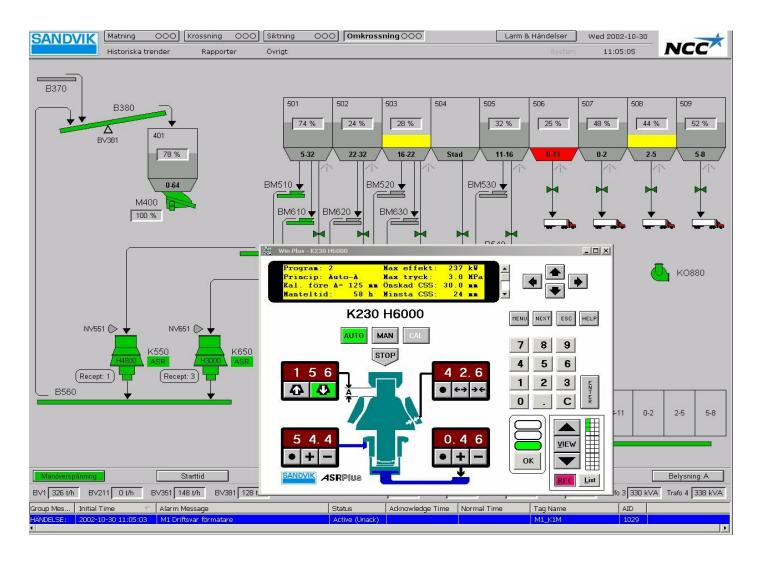








### **Joint Venture**

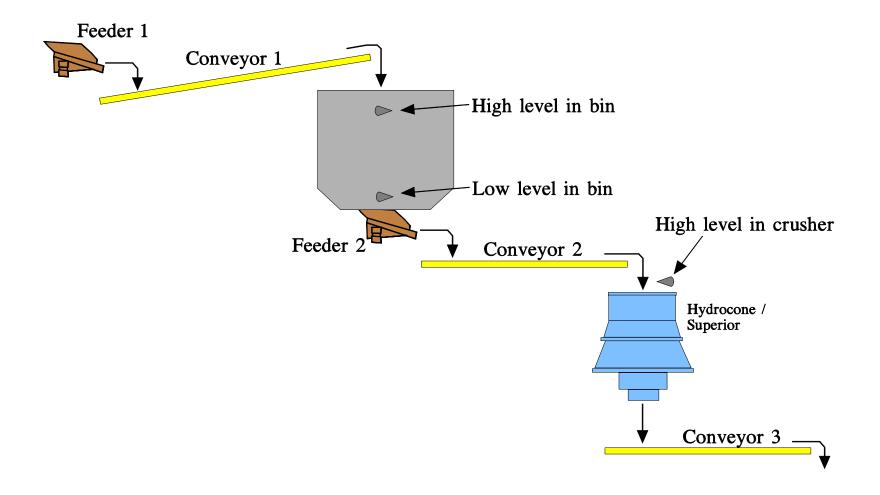








## **External automation systems**

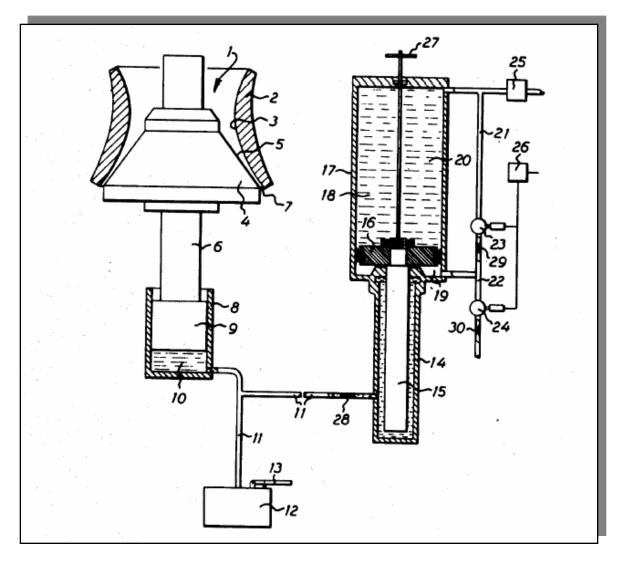








# The Harry Up System

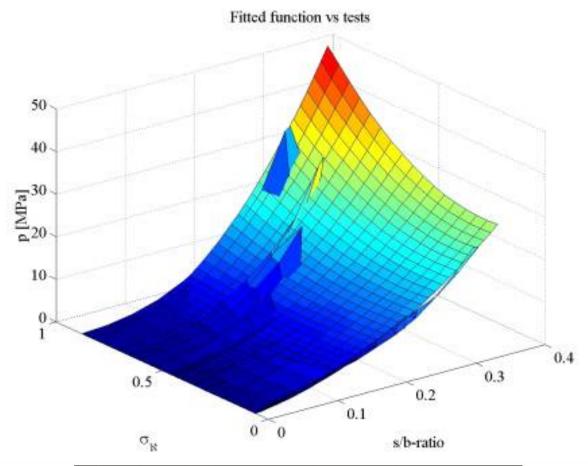








## Multi Interparticle Pressure



$$\begin{split} p\left(s_{\aleph},\sigma_{\aleph}\right) &= a_{1}s_{\aleph}^{2}\sigma_{\aleph}^{2} + a_{2}s_{\aleph}^{2}\sigma_{\aleph} + a_{3}s_{\aleph}^{2} + a_{4}s_{\aleph}\sigma_{\aleph}^{2} + a_{5}s_{\aleph}\sigma_{\aleph} + a_{6}s_{\aleph} \\ \sigma_{\aleph} &= \textit{size distribution width} \end{split}$$







# The advantages

- Can operate choke-fed and utilize the maximum motor power.
- > The reduction increases.
- The product shape gets better
- The liner life increase
- Overloading protections
- An automated crusher looks after it self.







### **Today**

- Intelligent automatic regulation system.
- The system have highly flexible and will improve the crushing results.
- Regulate the crusher and protects it from underload/overload.
- Advanced sensors.
- Automated rapid wear compensations.
- Simpler fully automated calibration modes.
- Easier and faster information access ways.
- Different and adopted regulation modes.
- Integrated approach towards process control computers.
- Comfortable connecting to the Internet.







## **ASRi**









### **GPS and Remote control**







